

AN ALGORITHM FOR REORIENTING INFINITE PSEUDO-TRANSITIVE GRAPHS

Marta Fiori Carones

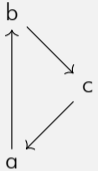
Joint work with Alberto Marcone

Theorem (Ghouila-Houri)

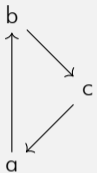
For each pseudo-transitive oriented graph there exists a transitive reorientation

A graph (V, \rightarrow) is pseudo-transitive if for each $a, b, c \in V$
if $a \rightarrow b \rightarrow c$ then either $a \rightarrow c$ or $c \rightarrow a$.

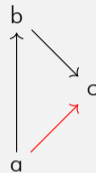
$(V, <)$ is a reorientation of (V, \rightarrow) if
 $a, b \in V$ are \rightarrow -comparable if and only if they are $<$ -comparable.



pseudo-transitive graph



pseudo-transitive graph



transitive reorientation

Theorem (Ghouila-Houri, Gilmore Hoffman)

If an undirected graph is such that every cycle of odd length has a triangular chord, then it is transitively orientable.

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Theorem (Hirst)

The following statement is NOT computably true:

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- there exists an on-line (incremental) algorithm to transitively reorient pseudo-transitive oriented graphs;

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There exists an on-line algorithm which takes as

INPUT a pseudo-transitive oriented graph (V, \rightarrow) (possibly infinite)

and gives as

OUTPUT a transitive oriented graph (V, \prec) such that $a \rightarrow b \Leftrightarrow a \prec b$

Theorem

- there exists an on-line (incremental) algorithm to transitively reorient pseudo-transitive oriented graphs;

Let $(\{v_n \mid n \in \mathbb{N}\}, \rightarrow)$ be a pseudo-transitive oriented graph

INPUT

at stage n the algorithm reads

- the n^{th} vertex v_n of (V, \rightarrow) ,
- the edges connecting v_n to $\{v_0, \dots, v_{n-1}\}$

At most n new bits
of information at
each step

OUTPUT

at stage n the algorithm outputs

- a transitive reorientation of all the edges connecting v_n to $\{v_0, \dots, v_{n-1}\}$,
- preserves the reorientations already set at previous stages

No mind changes

Theorem

- there exists an on-line (incremental) algorithm to transitively reorient pseudo-transitive oriented graphs;
- RCA_0 proves that every countable pseudo-transitive oriented graph has a transitive reorientation;
- every computable pseudo-transitive oriented graph has a computable transitive reorientation;
- the multi-valued function that maps a countable pseudo-transitive oriented graph to the set of its transitive reorientations is computable;
- Player II has a winning strategy for the following game: starting from the empty graph, at step $s + 1$ player I plays a pseudo-transitive extension $(V_s \cup \{x_s\}, \rightarrow_{s+1})$ of the pseudo-transitive oriented graph (V_s, \rightarrow_s) he played at step s . Player II replies with a transitive reorientation \prec_{s+1} of \rightarrow_{s+1} such that \prec_{s+1} extends \prec_s she defined at step s . Player II wins if and only if she is always able to play.

There exists an on-line algorithm which takes as

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Obstacles: transitive triangle

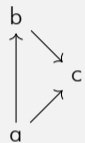


a

b

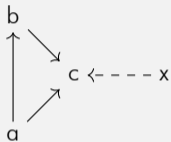
a \prec b

Obstacles: transitive triangle



$$a \prec c \prec b$$

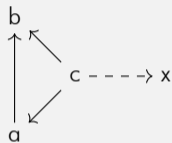
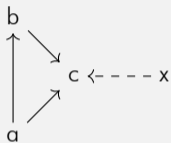
Obstacles: transitive triangle



$a \prec c \prec b$ is NOT extendible

(V, \rightarrow, \prec) is extendible if for every $(V \cup \{x\}, \rightarrow')$, pseudo-transitive extension of (V, \rightarrow) , there exists $\prec' \supseteq \prec$ transitive reorientation of $(V \cup \{x\}, \rightarrow')$

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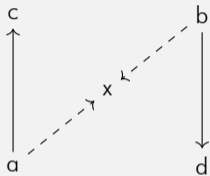
Obstacles: $2 \oplus 2$

c
↑
a

b
↓
d

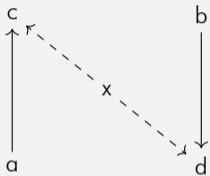
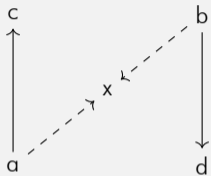
$a \prec c, \quad d \prec b$

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$a \prec c, d \prec b$ is NOT extendible

- we isolate the two possibly “problematic” situations
- we state two properties which must be preserved in order for a reorientation to be extendible
- we design an algorithm which preserves the properties, i.e. that the algorithm is correct and complete

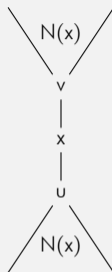
Let (V, \rightarrow) be a pseudo-transitive graph and \prec a transitive reorientation.

If $(V \cup \{x\}, \rightarrow')$ is a pseudo-transitive extension of (V, \rightarrow) let

$$N(x) = \{a \in V \mid a \rightarrow' x \vee x \rightarrow' a\}$$

$$N^+(x) = \{v \in N(x) \mid \forall w (v \prec w \Rightarrow w \in N(x))\};$$

$$N^-(x) = \{u \in N(x) \mid \forall w (w \prec u \Rightarrow w \in N(x))\}.$$



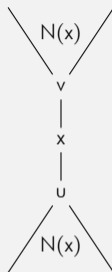
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If (V, \rightarrow, \prec) is extendible,

then for any $(V \cup \{x\}, \rightarrow')$ pseudo-transitive extension of (V, \rightarrow) we have:

- $N(x) = N^+(x) \cup N^-(x)$;
- $N^-(x) \setminus N^+(x) \prec N^+(x) \setminus N^-(x)$.

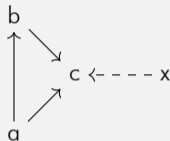
Back to transitive triangles

Let (V, \rightarrow) be a pseudo-transitive graph and \prec a transitive reorientation.

■ For any $(V \cup \{x\}, \rightarrow')$ pseudo-transitive extension of (V, \rightarrow) the following are equivalent:

(i) $N(x) = N^+(x) \cup N^-(x)$;

(ii) $\forall a, b, c \in V (a \prec c \prec b \wedge x \rightarrow' c \Rightarrow x \rightarrow' a \vee x \rightarrow' b)$.



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(ii) $\forall a, b, c \in V (a \prec c \prec b \wedge x -' c \Rightarrow x -' a \vee x -' b)$.

- Φ and Ψ are satisfied

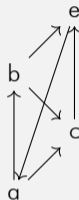
$\varphi(a, b, c) :=$ there exists $e_0, \dots, e_n \in V$ such that:

$(\varphi_1) \quad c \rightarrow e_0$;

$(\varphi_2) \quad \forall i < n ((a \rightarrow e_i \wedge b \rightarrow e_i \rightarrow e_{i+1}) \vee (e_{i+1} \rightarrow e_i \rightarrow b \wedge e_i \rightarrow a))$;

$(\varphi_3) \quad a \rightarrow e_n \rightarrow b \vee b \rightarrow e_n \rightarrow a$.

Then Φ is $\forall a, b, c \in V (a \rightarrow c \leftarrow b \wedge a \prec c \prec b \Rightarrow \varphi(a, b, c))$



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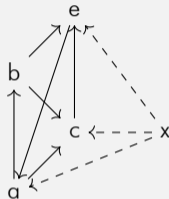
$\varphi(a, b, c) :=$ there exists $e_0, \dots, e_n \in V$ such that:

(φ_1) $c \rightarrow e_0$;

(φ_2) $\forall i < n ((a \rightarrow e_i \wedge b \rightarrow e_i \rightarrow e_{i+1}) \vee (e_{i+1} \rightarrow e_i \rightarrow b \wedge e_i \rightarrow a))$;

(φ_3) $a \rightarrow e_n \rightarrow b \vee b \rightarrow e_n \rightarrow a$.

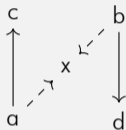
Then Φ is $\forall a, b, c \in V (a \rightarrow c \leftarrow b \wedge a \prec c \prec b \Rightarrow \varphi(a, b, c))$



Back to $2 \oplus 2$

Let (V, \rightarrow) be a pseudo-transitive graph and
 \prec a transitive reorientation which satisfy Φ and Ψ .

- For any $(V \cup \{x\}, \rightarrow')$ pseudo-transitive extension of (V, \rightarrow)
the following are equivalent:
 - $N^-(x) \setminus N^+(x) \prec N^+(x) \setminus N^-(x)$;
 - $\forall a, b, c, d \in V (a \mid b \wedge c \mid d \wedge a \prec c \wedge d \prec b \wedge x -' a \wedge x -' b \Rightarrow x -' d \vee x -' c)$.

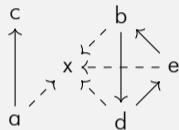


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 - $\forall a, b, c, d \in V (a \mid b \wedge c \mid d \wedge a \prec c \wedge d \prec b \wedge x -' a \wedge x -' b \Rightarrow x -' d \vee x -' c)$.
- Θ is satisfied



Back to $2 \oplus 2$

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- Θ is satisfied

$\theta(a, b, c, d) :=$ there exists $e_0, \dots, e_n \in V$ such that:

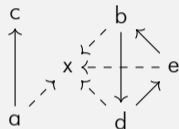
(θ_1) $e_0 \rightarrow b$;

(θ_2) $\forall i < n (e_{i+1} \rightarrow e_i \rightarrow d)$;

(θ_3) $d \rightarrow e_n$;

(θ_4) $e_n \mid a$.

Then Θ is $\forall a, b, c, d \in V (a \rightarrow c \wedge b \rightarrow d \wedge a \mid b \wedge c \mid d \wedge a \prec c \wedge d \prec b \Rightarrow \theta(a, b, c, d) \vee \theta(b, a, d, c))$



Algorithm

Let (V, \rightarrow) be a pseudo-transitive oriented graph and \prec a reorientation.

If $(V \cup \{x\}, \rightarrow')$ is a pseudo-transitive extension of \rightarrow , we define inductively the following subsets of $N(x)$:

$$S_0^-(x) = N^-(x) \setminus N^+(x);$$

$$S_0^+(x) = N^+(x) \setminus N^-(x);$$

$$S_i(x) = S_i^-(x) \cup S_i^+(x);$$

$$S_{i+1}^-(x) = \{a \in N(x) \setminus \bigcup_{j \leq i} S_j(x) \mid \exists s \in S_i^-(x)(a \mid s)\};$$

$$S_{i+1}^+(x) = \{a \in N(x) \setminus \bigcup_{j \leq i} S_j(x) \mid \exists s \in S_i^+(x)(a \mid s)\}.$$

Let $S^+(x) = \bigcup_{i \in \mathbb{N}} S_i^+(x)$, $S^-(x) = \bigcup_{i \in \mathbb{N}} S_i^-(x)$.

Let $T(x) = N(x) \setminus S(x)$.

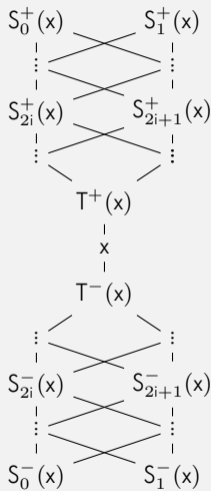
Algorithm

INPUT $(\{v_n \mid n \in \mathbb{N}\}, \rightarrow)$ pseudo-transitive oriented graph

PARTIAL OUTPUT $(\{v_0, \dots, v_n\}, \prec)$ transitive reorientation

A STEP $(\{v_0, \dots, v_n, x\}, \prec')$ such that for each $i \leq n$

- if $v_i \notin N(x)$ let $v_i \not\prec' x$ and $x \not\prec' v_i$,
- if $v_i \in S^-(x)$ let $v_i \prec' x$,
- if $v_i \in S^+(x)$ let $x \prec' v_i$,
- if $v_i \in T(x)$ then
 - (a) if there exists $j < i$ such that $v_i \prec v_j \prec' x$ let $v_i \prec' x$,
 - (b) if there exists $j < i$ such that $x \prec' v_j \prec v_i$ let $x \prec' v_i$,
 - (c) otherwise let $v_i \prec' x$ if $v_i \rightarrow' x$
and $x \prec' v_i$ if $x \rightarrow' v_i$.



A STEP $(\{v_0, \dots, v_n, x\}, \prec')$ such that for each $i \leq n$

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 - (c) otherwise let $v_i \prec' x$ if $v_i \rightarrow' x$ and $x \prec' v_i$ if $x \rightarrow' v_i$.

We need to check that

- \prec' is a reorientation
- \prec' is transitive

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If $S^-(x) \cap S^+(x) = \emptyset$ and $S(x) \cap T(x) = \emptyset$,
then \prec' is a reorientation

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We need to check that

- \prec' is a **reorientation**
- \prec' is transitive

If $(\{v_0, \dots, v_n\}, \rightarrow), \prec$ satisfy Φ, Ψ and Θ ,
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We need to check that

- Φ, Ψ, Θ are satisfied
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INPUT $(\{v_n \mid n \in \mathbb{N}\}, \rightarrow)$ pseudo-transitive oriented graph

**PARTIAL
OUTPUT** $(\{v_0, \dots, v_n\}, \prec)$ transitive reorientation

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$(\{v_0, \dots, v_n\}, \prec)$ transitive reorientation \Rightarrow

\prec satisfy $\Phi, \Psi, \Theta \Rightarrow$

$(\{v_0, \dots, v_n, x\}, \prec')$ transitive reorientation

We need to check that

- Φ, Ψ, Θ are satisfied
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INPUT $(\{v_n \mid n \in \mathbb{N}\}, \rightarrow)$ pseudo-transitive oriented graph

PARTIAL OUTPUT $(\{v_0, \dots, v_n\}, \prec)$ transitive reorientation

$(\{v_0, \dots, v_n\}, \prec)$ transitive reorientation \Rightarrow

\prec is **lazy** \Rightarrow

\prec satisfy $\Phi, \Psi, \Theta \Rightarrow$

$(\{v_0, \dots, v_n, x\}, \prec')$ transitive reorientation

If $v_i \rightarrow v_j$ and $v_j \prec v_i$
there exists v_h such that
 $v_i \rightarrow v_h \rightarrow v_j$,
 $v_j \prec v_h \prec v_i$, and
 $h < \min(i, j)$

Complexity

The complexity of the algorithm is $O(|V|^3)$.

The problem of orienting comparability graphs can be solved by an algorithm with complexity $O(\delta \cdot |E|)$, where δ is the maximum degree of a vertex

Complexity

The complexity of a step of the algorithm is $O(|V|^2)$.

- at most $|V^2|$ steps to compute $S_0^+(x)$ and $S_0^-(x)$
- the remaining members of $S^+(x)$ and $S^-(x)$ can be found by a depth-first search algorithm applied to the non-adjacency graph $(V \cup \{x\}, E')$ ($O(|V| + |E|)$)
- the rest is linear

The problem of orienting comparability graphs can be solved by an algorithm with complexity $O(\delta \cdot |E|)$, where δ is the maximum degree of a vertex