# Nondeterminism and Analog Computation: towards a characterization of **NP**

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  - A characterization of **P** by polynomial differential systems ([Pou15])

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  - Unification of approaches via the length of the curve
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Two characterizations of P



Figure 1: A differential analyser

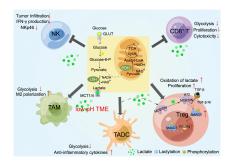


Figure 2: A natural model ([SLH22])

- 1941 : General Purpose Analog Computer (GPAC) ([Sha41])
- Association of basic blocks  $(k,+,-,\times,\int)$  to build circuits

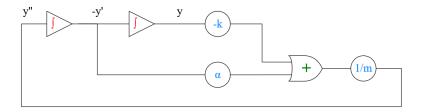


Figure 3: A damped harmonic oscillator

$$y'' = \frac{1}{m}(-ky - \alpha y')$$

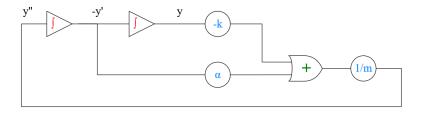


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■ Function **generated** by a GPAC : y' = p(y),  $p \in \mathbb{R}[X]$ 

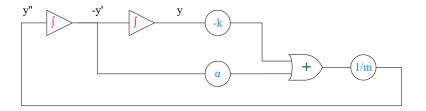


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$$y'' = \frac{1}{m}(-ky - \alpha y')$$

- Function **generated** by a GPAC : y' = p(y),  $p \in \mathbb{R}[X]$
- It is rather the *trace* of the computation...

Two characterizations of P

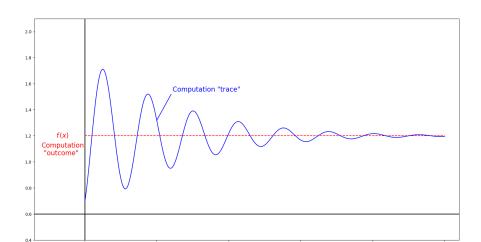


Figure 4: Computation outcome v. Computation trace

Temps

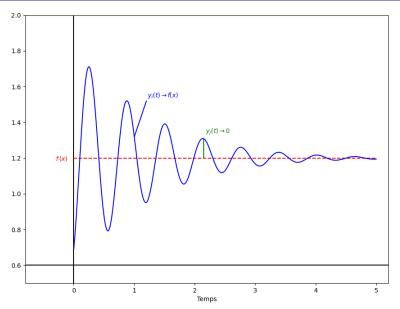
#### Definition

 $f:[a,b] \to \mathbb{R}$  is **GPAC-computable** iff there exists  $p:\mathbb{R}^{n+1} \to \mathbb{R}^n$  a polynomial,  $p_0 \in \mathbb{R}[X]$ ,  $\alpha_1, \ldots, \alpha_{n-1} \in \mathbb{R}_c$  such that for  $x \in [a,b]$ , if  $y \in \mathbb{R}^n$  is the solution of

$$Y'=p(Y,t)$$

with initial condition  $Y_0 = (\alpha_1, \ldots, \alpha_{n-1}, p_0(x))$ , we have :

$$\exists \, (i,j) ext{ such that } egin{cases} \lim_{t o \infty} y_j(t) = 0 \ |f(x) - y_i(t)| \leq y_j(t) \end{cases}$$



Two characterizations of P

# Theorem ([BCGH06])

f is GPAC-computable



f is computable in the sense of computable analysis

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- ← We can simulate TM with polynomial systems. How can we iterate a (transition) function with such a system?

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$$\begin{cases} z'_{1} = (f(z_{2}) - z_{1})^{3} \phi(t) & "z_{1} \leftarrow f(z_{2})" \\ z'_{2} = (z_{1} - z_{2})^{3} \phi(-t) & "z_{2} \leftarrow z_{1}" \end{cases}$$

Computability

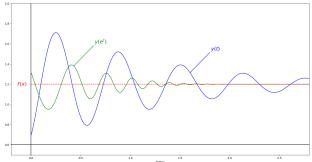


- Computability
- Complexity ?

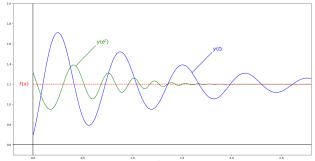
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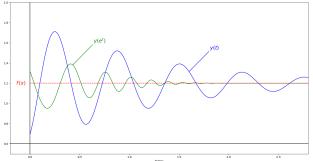


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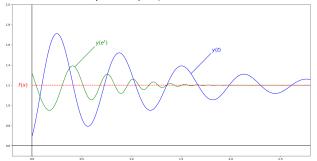
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■ Curve length? (invariant by reparametrization) ✓

## Theorem ([Pou15])

f is (classically) polynomial-time computable

f is GPAC-computable by a GPAC of polynomial length

...by analytic functions

Another characterization with analytic functions by [Thi18]

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Unification and canonical representative

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#### Theorem ([Mü95])

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■ We need more information

...by analytic functions

$$f:[0,1] o\mathbb{R}$$
 analytic.

#### Definition

A name for f consists of  $(A, K, (a_{m,n})_{m \le 2K, n \ge 0})$  such that :

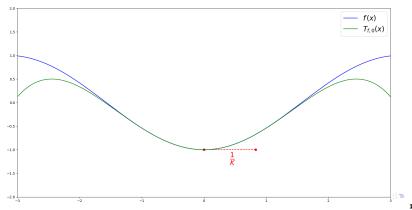
- $a_{m,n}$  is the *n*-th Taylor's coefficient of f around  $\frac{m}{2K}$
- $|a_{m,n}| \leq AK^n$

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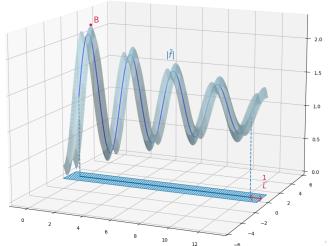
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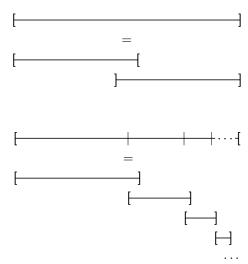
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■ More natural to talk about analytic functions on open intervals



...by analytic functions

### Theorem ([Thi18])

 $F:[0,1] \to \mathbb{R}$  analytic, A, K the parameters of its name. The solution of y'=F(y) (with initial condition  $y_0 \in [0,1]$ ) can be approximated up to  $2^{-n}$  in a time polynomial in (n+A+K).

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- Link with [Pou15] (characterization by the GPAC) ?
- Extension to NP ?

How can one add nondeterminism in a polynomial system ?

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## Lemma (Definition of **NP** by certificate)

$$L \in \mathbf{NP} \iff \exists L' \in \mathbf{P} \text{ such that } \forall x,$$
  
 $x \in L \iff \exists w, |w| \leq poly(|x|) \text{ and } (x, w) \in L'$ 

Modification of Branicky's trick:

$$\begin{cases} z_1' = (f(z_2, A(t)) - z_1)^3 \phi(t) \\ z_2' = (z_1 - z_2)^3 \phi(-t) \end{cases}$$

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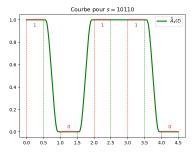


Figure 5: Ideal A(t)

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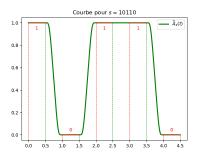


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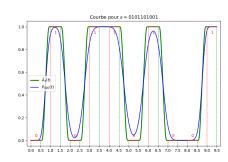


Figure 6: Analytic A(t)

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#### Theorem

One can explicit a polynomial whose degree and coefficients are **quadratic** in T that approximates A(t) at a given precision on [0,T].

#### Proof.

Use Bernstein polynomials.

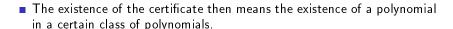
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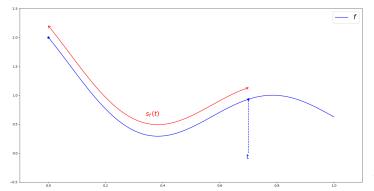
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# Definition (Abscisse curviligne)

$$f \in \mathcal{C}^1([0,1],\mathbb{R})$$
,  $L = \mathsf{len}(f)$ . We call abscisse curviligne of  $f$ :

$$s_f: [0,1] \longrightarrow [0,L]$$
  
 $x \longmapsto \mathsf{len}_{[0,x]}(f)$ 

That is:  $s_f(t) = \int_0^t \sqrt{1 + f'(x)^2} \, dx$ 



## Theorem (Link name/length of the curve)

 $f:[0,1]\to\mathbb{R}$  analytic. From a name of f, one can compute a name for  $s_f$  in polynomial time (and  $A_{s_f},K_{s_f}$  are themselves polynomial in  $A_f,K_f$ ).

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■ Consequence : one can compute  $len(f) = s_f(1)$  from a name of f, and its value is polynomial in the parameters of f.

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